



CIB Student Chapter

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A Derivative-free Optimization Approach for Automated As-built 3D Modelling

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Outline

1

Background & Opportunity

2

As-built Modeling via Optimization

3

Discussion & Future Research

The background of the slide is a painting of a large, classical-style building with a prominent clock tower on the right side. The building features a long colonnade of columns. In the foreground, there are lush green and reddish-brown trees and foliage. The overall style is artistic and painterly.

Section 1

BACKGROUND & OPPORTUNITY



1.1 As-built 3D modeling of civil infrastructures

◆ As-built models ^[1]

▣ Increasingly important for AEC/FM[†]

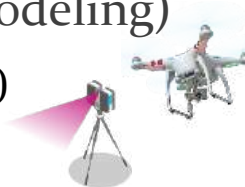
- Construction management
- Facility management
- Built env. conservation
- Business with VR/AR, *etc.*



▣ See as-planned, as-designed, as-demolished BIM^[2]

◆ Popular technologies (surface modeling)

- ▣ Photogrammetry (videogrammetry)
- ▣ Point cloud
- ▣ 3D Geographic information system
- ▣ Others (statistical rules, deep learning ^[3], *etc.*)



An example of photogrammetry: Kowloon Wall City
(Source: patrick-@sketchfab.com)



An example of point cloud: Pompei City
(Source: MAP-Gamsau lab, CNRS, France)



An example of GIS-based: 3D Berlin
(Open Data, source: berlin.de)

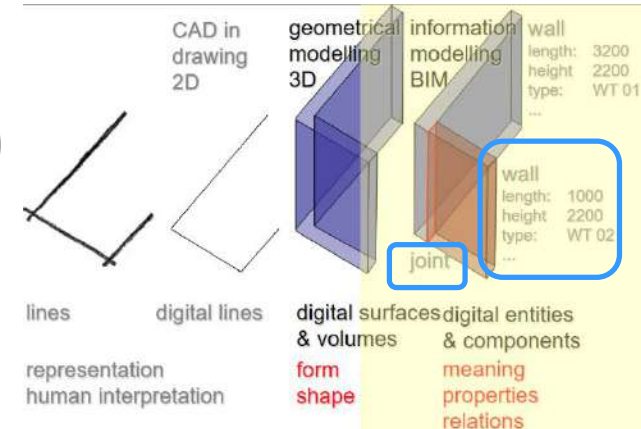


1.1 Final goal: Semantically rich as-built BIM

- ◆ BIM (building information model, narrow sense)^[2]
 - ▣ The digital representation of physical and functional characteristics of a facility
 - ▣ A shared knowledge resource for information about a facility serving as a reliable basis for decisions making
- ◆ Two types of semantic information in BIM^[2, 4-5]
 - ▣ *Attributes* of an individual construction component
 - geometric (*e.g.*, size, position, shape, & textures)
 - non-geometric (*e.g.*, type, material, & functions)
 - ▣ *Relationships* between components
 - *E.g.*, dependency, topology, and joints



A word cloud of BIM
(Source: advenser.com)



An evolution view of CAD model/BIM ^[6]



1.1 Final goal: Semantically rich as-built BIM

◆ Semantically rich as-built BIM

▣ *Actual* building geometries, *current* function, *real* topology, etc.

○ In addition to the surface of the building envelope

▣ Advancing the knowledge frontiers of

○ Smart city applications

○ Healthy aging scenarios

○ Robotics and computer vision

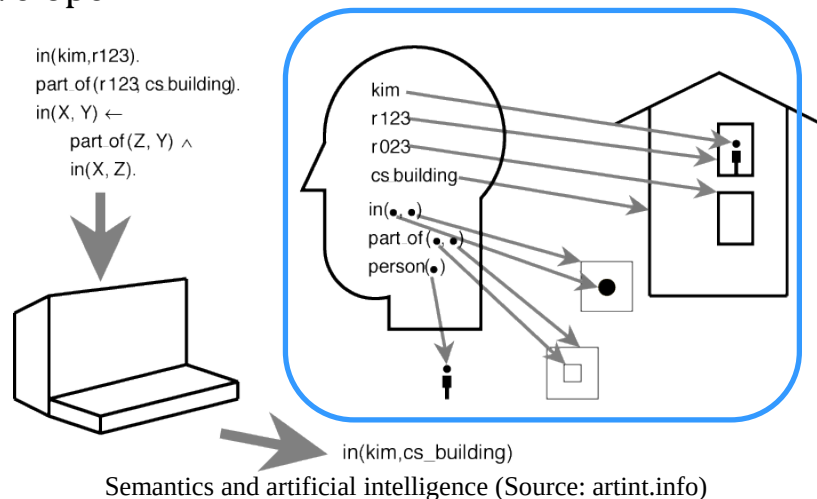
○ Artificial intelligence, etc.

▣ Downward compatibility

○ Methods and technologies *should* also work with as-built 3D building models

▣ Relating standards

○ LOD (CityGML level of details^[7]), IFC^[8], etc.





1.2 The (semi-)automated modeling methods

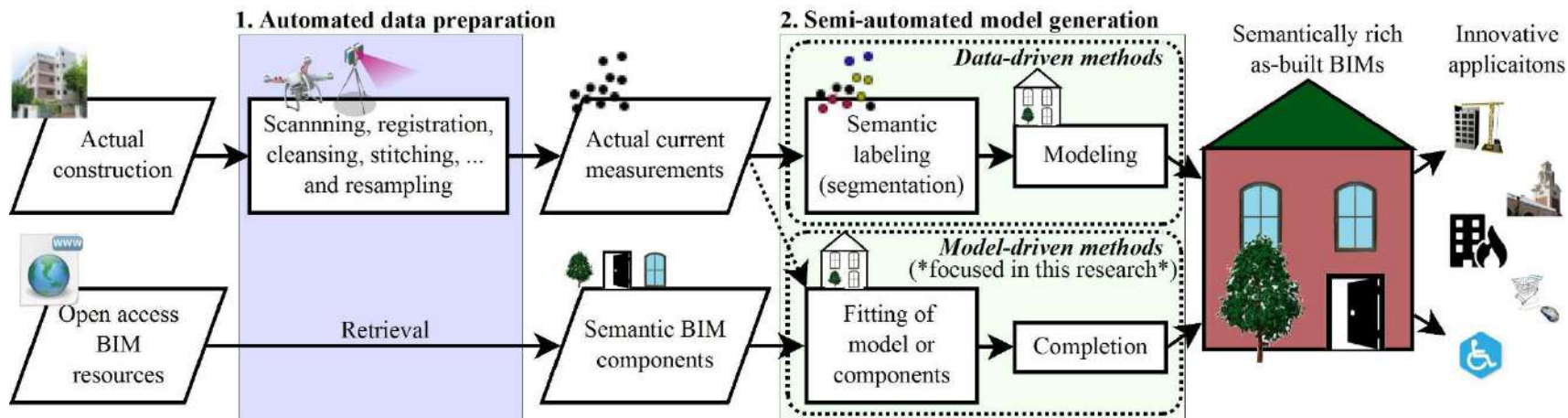
◆ Two categories of methods (for both)

▣ Data-driven: On (pre-processed) point clouds or images

- Poisson mesh surface, RANSAC planes/spheres, edge detection, image segmentation, *etc.*

▣ Model-driven: Recognizing & fitting the known (BIM) components against the data

- Evolutionary fitting of components, context-based region growing, VR of pipes/ribbons...





1.2 The limitations



◆ Limitations of existing methods

▣ Data-driven

- Unsatisfactory semantic/abstraction discovery

Huge model size

- Automation level of modeling

Tedious and error-prone manual work

- High requirement on measurement data

Expensive equipment

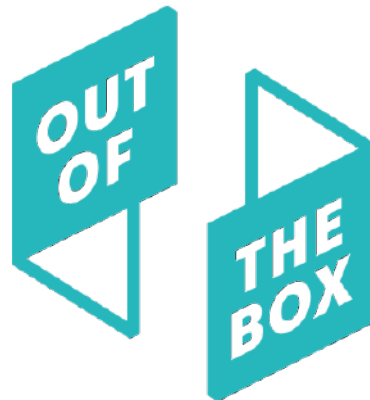
▣ Model-driven

- *Ad-hoc* project setting/ context

Poor reusability

◆ Thinking out of the box

- ▣ Exposing the modeling process to general decision science/OR study





1.3 Derivative-free Optimization in OR[†]

◆ Optimization (a.k.a. Mathematical programming)

- ▣ the selection of a *best* element (with regard to some criteria) from *some* set of available alternatives.

◆ Nonlinear optimization

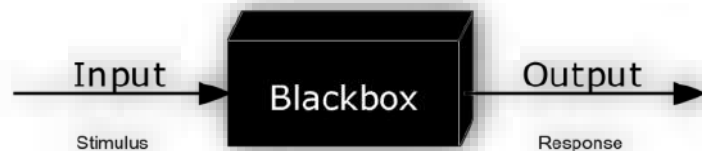
- ▣ When *objective function* or some *constraints* are nonlinear

◆ Derivative-free Optimization (DFO) [9]

- ▣ *Objective function* or *constraints* are *unknown*
 - E.g., model selection, parameter tuning in simulations
 - Especially when function is *very expensive* or *unanalyzable*
- ▣ Challenging (*NP-hard*), but achieved significant success
 - In applied science and engineering such as *molecular biology* and *material sciences*

$$\max f: \mathbb{R}^n \mapsto \mathbb{R}$$

An example of optimization



DFO: Manipulating a black-box
(Figure adapted from Wikipedia)

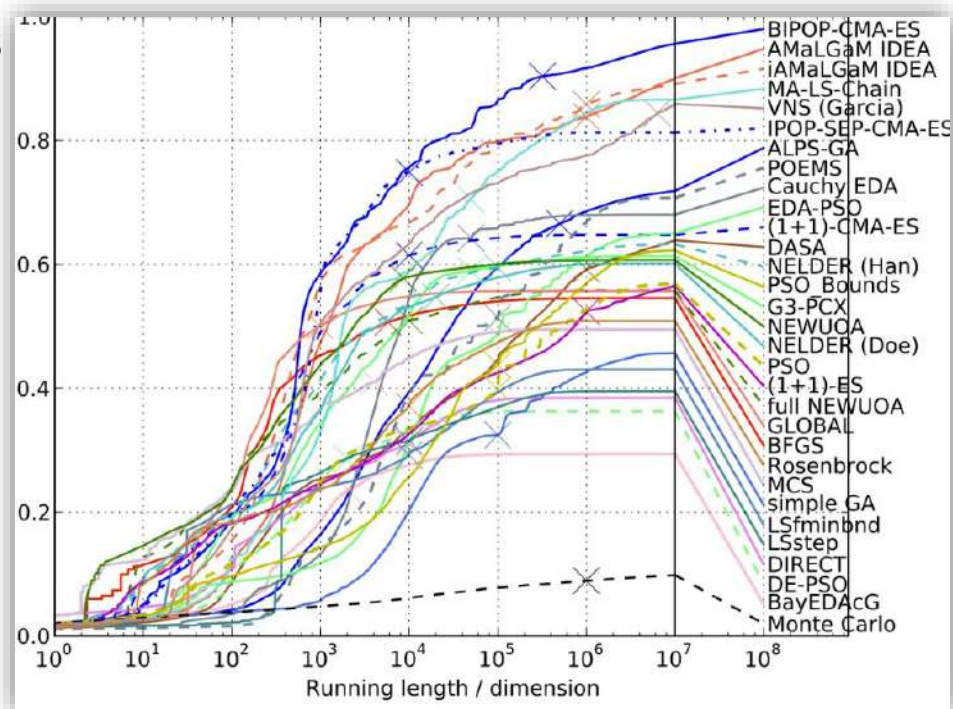
[†]: Operations Research



1.3 Derivative-free Optimization methods

◆ A long list of off-the-peg algorithms for solving optimization problems as a black-box:

- ▣ Surrogate methods
 - CMA-ES (Covariance matrix adaptation with evolution strategy) ^[11] and its variants are competitive
- ▣ Trust-region methods
- ▣ Metaheuristics (GA, PSO, VNS, *etc.*)
- ▣ Hyper-heuristics, data mining
- ▣ ... and Monte Carlo



Comparison of algorithms for BBOB-2009 (Black-Box Optimization Benchmarking, higher is better) ^[10]



1.4 An opportunity



◆ The questions

▣ *Can the model generation be generally solved by DFO methods?*

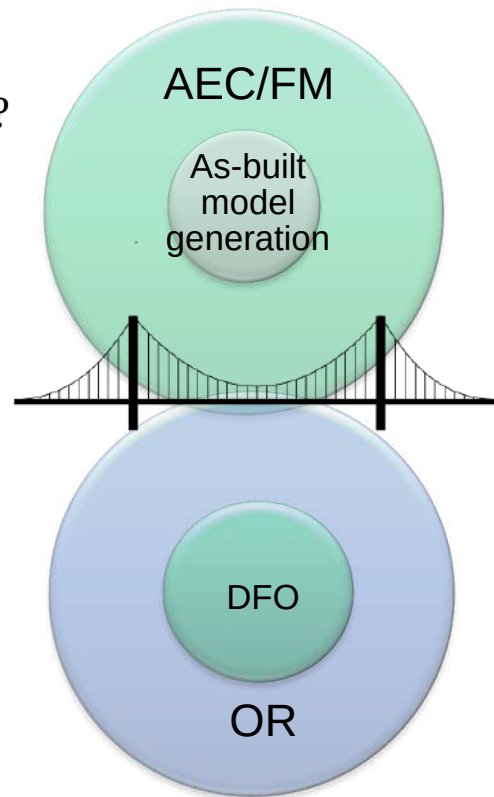
○ *If true, can semantic data be discovered at the same time?*

◆ If all true, we can

▣ Map between a typical problem in AEC/FM and a class of powerful algorithms in OR

○ Also expose as-built model generation to many other nonlinear methodologies

▣ Discover semantic (abstraction) information



The background of the slide is a photograph of a large, ornate building with a clock tower, likely a university or government building. The building is light-colored with many windows and columns. In the foreground, there are lush green trees and some red flowers. The sky is blue with some light clouds.

Section 2

AS-BUILT MODELING AS OPTIMIZATION



2.1 A meta-model of as-built 3D modeling

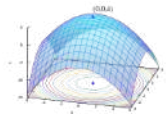


◆ Given a reference **measurement**, a set of parametric **components**

◆ A meta-model of constrained optimization is from such a formulation:

$$\max f(X)$$

$$\text{s.t. } C(X) \leq 0$$



Meta-model of constrained optimization & its solution space

Tells computers:

What to change

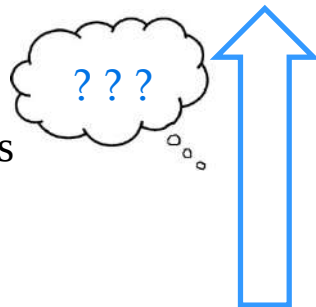
What is good

Rules to follow

- The **variables** (X) are the parameters of the components;
- The **objective function** (f) is to maximize the similarity (or minimize dissimilarity) between the 3D model (as combinations of the parametric components) and the measurement; and
- The **constraints** (C) over the variables are the topological relationships between components.

◆ Meta-: Abstraction

□ from Greek prefix *μετά*-, “beyond”



Reference measurements

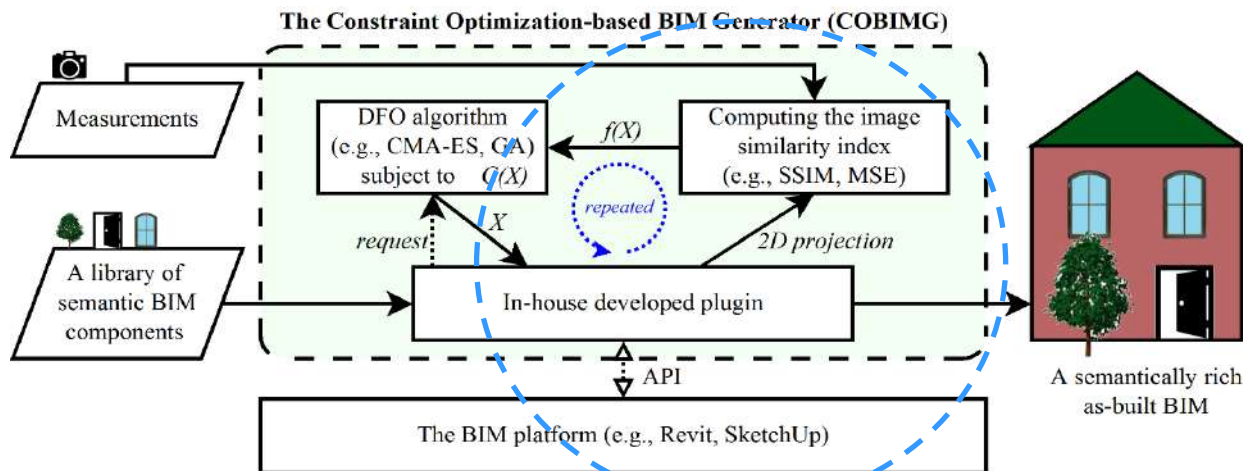


Parametric (& semantic) components



2.1 The framework: A bird's-eye view

- ◆ The full framework (using photo measurement as an example)
 - ▣ Input 1: Reference measurements (photos)
 - ▣ Input 2: Semantic and parametric components
 - ▣ Process: Systematically finding the fittest model by solving meta-model with DFO methods
 - ▣ Output: A semantic as-built model





2.1 Formulation of the meta-model

◆ The variables

□ $X_i = \langle cl, l, s, r_z \rangle$ for each i -th component instance

○ cl : class, l : location, s : scaling, r_z : rotation-z

◆ The objective function^[12] (similarity between A & $\hat{A}$)

□ $SSIM = structure \cdot luminance \cdot contrast = \frac{(2\mu_{\hat{A}}\mu_A + c_1)(2\sigma_{\hat{A}A} + c_2)}{(\mu_{\hat{A}}^2 + \mu_A^2 + c_1)(\sigma_{\hat{A}}^2 + \sigma_A^2 + c_2)}$

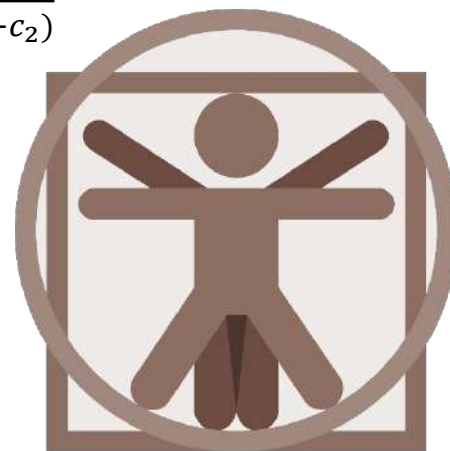
□ $Similarity = 1 - MSE = 1 - \frac{1}{n} \sum_{i=1}^n (\hat{A}_i - A_i)^2$

◆ The constraints

□ $C(X) = \{C_I(X_i)\} \cup \{C_R(X_i, X_j), i \neq j\},$

○ C_I : about individual component X_i

○ C_R : the topological relationships between any (i -th, j -th) components





2.1 Details of the topological relationships

◆ Topological relationships

▣ Categories

- Adjacency: ON_TOP_OF, BELOW, NEXT_TO, ...
- Separation: SEPERATED
- Containment: CONTAINS_ON, CONTAINS_IN
- Intersection: INTERSECTS_WITH
- Connectivity: CONNECTS_TO

◆ Semantic definition

- ▣ Adding properties like *scaling* and *topological relationships* to their SketchUp dictionaries
 - E.g., ON_TOP_OF, BELOW, CONTAINS_ON, etc.



An example of the dictionary of component in SketchUp



2.2 A pilot: A demolished building at campus



◆ The pilot case

- ▣ A demolished baroque-style two-storey building
 - Once occupied by School of Tropical Medicine and School of Pathology, HKU

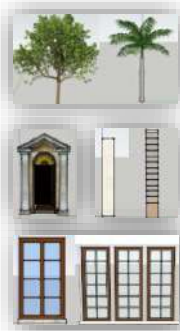
- ▣ Input: A photo

◆ Preparing parametric components

- ▣ Only apparent (>1m) components
 - 1 door portico, 1 tree (unknown type), 2 storeys of walls (...)
 - 5 identical windows on 1/F, 4 on G/F (all unknown types)
- ▣ 7 components were collected from *3D Warehouse* of *SketchUp*
 - With a keyword filter “*baroque*”
 - With limited (3) pairs of conflicting components
 - Adjustment: Removing extra parts, alignment



A historical photo (Source: MTR HKU Station, re-photographed by an Android phone)



- ▣ Door portico
- ▣ Tree × 2
- ▣ Wall × 2
- ▣ Windows × 2

(Contributors: Mohamed EL Shahed, Richard, KangaroOz 3D, Yoshi Productions, 3dolomouc, Architect, Ben @ 3D Warehouse)



2.2 The problem

◆ Meta-model of as a constrained optimization problem

- ▣ Minimize the dissimilarity
 - Between the projected image of model and the input photo
 - Similarity metric is the SSIM
- ▣ With respect to topological constraints
- ▣ Computational functions implemented on SketchUp (2016 Pro) Ruby API
 - Objective function interface
 - Variables as parameters (per component)
 - Manifolds (0, 1) + scaling (xyz) + location (xyz) + ~~rotation~~
 - ~~(α, β, γ)~~ = 4 ~ 6 variables
 - Constraints of topological relationships
- ▣ An invisible *Ground* object is placed at first

min $f = \text{SSIM}$

s.t. Semantic constraints of *position*, *scaling*, and *ABOVE/ BELOW/ CONTAINS_ON* for each component



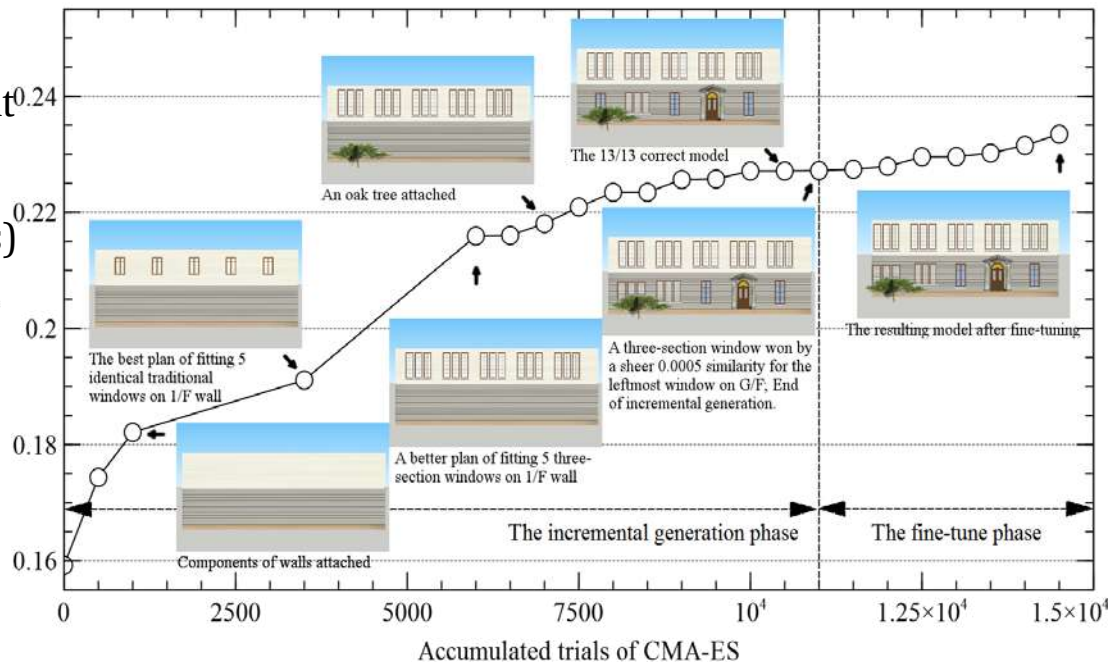
2.2 A computational experiment

◆ Automated generation

- 200 trials per target component^{0.24}
- Two phases:
 - Incremental (11,000 trials)
 - Refinement (3,500 trials)
- The Solver: CMA-ES (C++ code^[13] in a Ruby wrapper)
- Time: 5,012.6s

◆ Observation

- Fully automatic
- Fault-tolerant (see the windows)
- Semantic/grammar-enhanced



The automated optimization process of the proposed method with annotated SketchUp models in the test with 500 trials for fitting each component (The incremental generation phase: 1~11,000; The fine-tuning phase: 11,001~14,500)



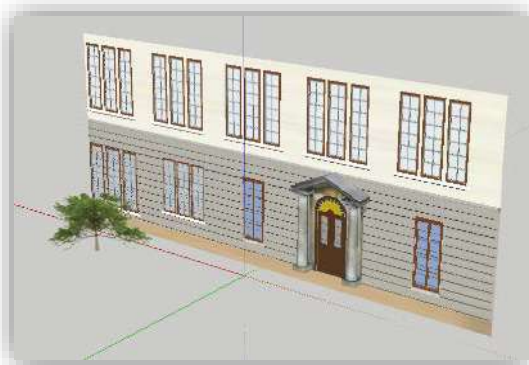
2.2 Results and post-processing

◆ Obtained

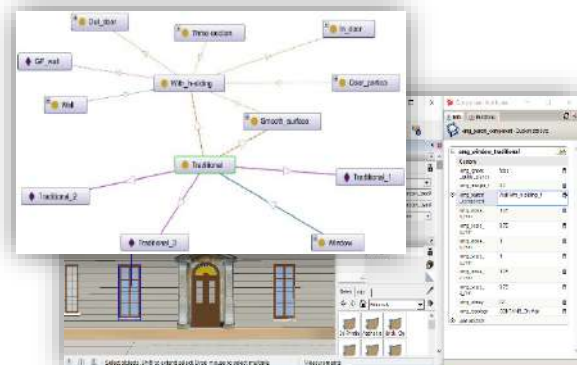
- ▣ The facade in the photo
- ▣ Semantic links

◆ Post-processing

- ▣ Manual completion
 - Copy & paste
- ▣ Georeferencing and display in 3D



(a) Direct result: The façade in the photo



(b) The semantic links illustrated in Stanford Protégé (Circle denotes a component class and a diamond stands for an instance/object)



(c) Manually completed approximate model (~15 minutes)



(d) Georeferencing and illustration on Google Earth, near MTR Exit A (~5 minutes) 20



2.2 The number of trials is critical



◆ When increasing the number of trials per component 10 to 1,000

▣ both the similarity and overall time cost were *monotonically* increasing

▣ Similarity

○ From 0.16 to over 0.24

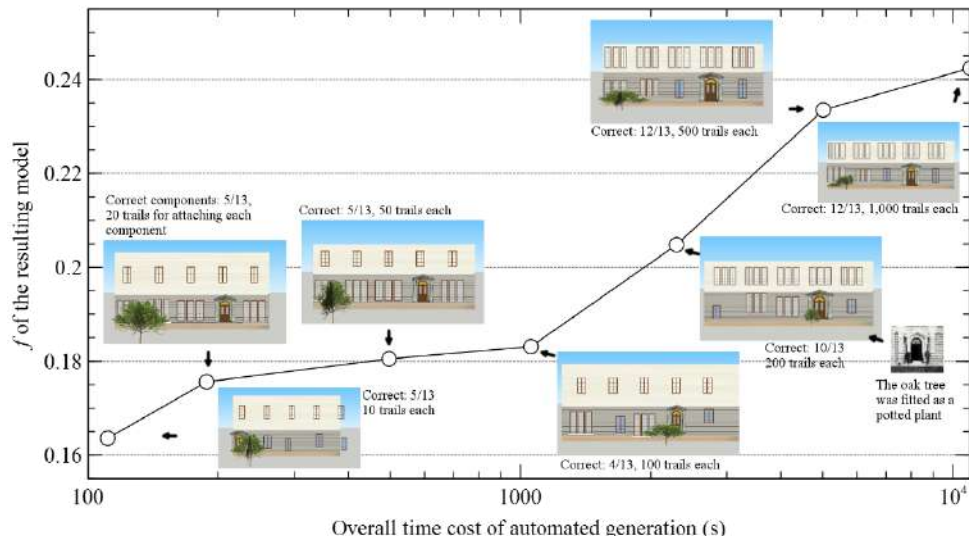
▣ Correct components

○ From 4~5/13 to 12/13

▣ Time cost: From 100+s to 10,000+s

○ Over 97% was consumed by BIM environment

1. Manipulations
2. Projections



The trends of similarity, overall time cost, and correctly generated components when changing the trails of CMA-ES for fitting each component

Used by	Functions	%time
SketchUp	Manipulating components; 3D to 2D projection	97.67%
Similarity	Computing the image similarity index	1.45%
DFO	Optimizing the parameters of a component	0.00%
System	Reading/writing of temporary image files	0.88%



3.3 COBIMG & live demonstration



◆ A library COBIMG (constrained optimization-based BIM generator) is under development

▣ A shared computational library with specific plugins for

○ SketchUp, Revit (soon), *etc.*

▣ Multiple meta-models with various

○ Objective functions

○ Measurement types, and

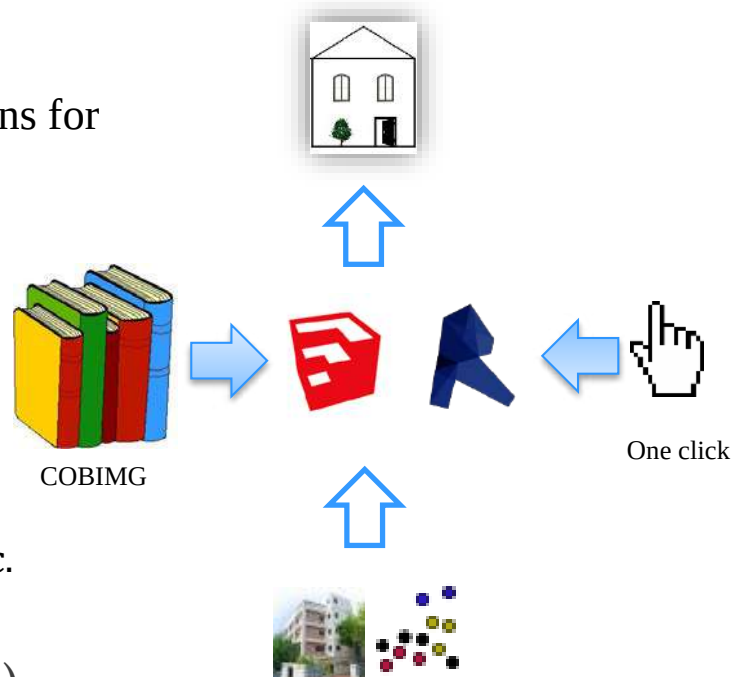
○ Solving algorithms

▣ Multiple modeling options

○ Ontology-guided, free discovery, finetuning, *etc.*

○ Extended the earlier pilot study

◆ Demo (Known sum of types for a quick demo)



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Section 3

DISCUSSION & FUTURE RESEARCH



3.1 Discussion



- ◆ Meta-modeling of as-built 3D modeling as constrained optimization
 - ▣ Pros: General, simple, no explicit object recognition/segmentation (also challenging)
 - ▣ Cons: A larger search space (slower), slow full projection, limited by pixels, less accurate
- ◆ Semantic definitions of components
 - ▣ Pros: Realized ‘grammar’ of components, simplified optimization
 - ▣ Cons: Some manual work needed, subject to redefinition from a project to another
- ◆ The framework as a whole
 - ▣ Pros: High automation, linearly incremental time, reusing components and abstractions, less requirements on equipment, tolerant to errors, (hopefully) semantically rich
 - ▣ Cons: Less accurate in geometry, still in its *infancy*
 - ▣ Answers to the question: 1) True; 2) Applicable to some relations
 - Semantic recognition/segmentation is another pillar for semantic BIM



3.2 Future research



◆ Effectiveness

- ▣ More domains (e.g. infrastructures, *etc.*)
- ▣ Advanced DFO methods
- ▣ More objective functions
- ▣ On real BIM/CIM models instead of surface models



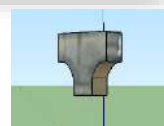
We are still on the way (Source: clipartpanda.com)

◆ Efficiency

- ▣ Efficient ways of manipulating point clouds (working...)
 - E.g., kd-tree, approximate k NN, convex hull, planar and object detection

◆ Extensions

- ▣ Shared component libraries for reusability (e.g., IFC-compatible)
- ▣ Handling other challenging AEC/FM problems



The Roman aqueduct Pont du Gard
(Source: Wikipedia/ 3Dwarehouse.com)²⁵



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Thank You !



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