



THE UNIVERSITY OF HONG KONG 香港大學
faculty of architecture 建築學院



iLab | @HKURBAN
the urban big data lab

2023智慧城市与智能建造高端论坛
暨中国建筑学会智能建造学术委员会年会

综合无监督、监督和强化学习的全自动 Scan2BIM

Fully Automatic Scan-to-BIM:

Consolidation of unsupervised, supervised, and reinforced learning

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5 May 2023, Smart City and Construction Forum, Wuhan, China





Outline



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背景 Introduction

关键词



概述 Types of Machine Learning

“训练?”



自动化 Automatic scan-to-BIM

“综合”

Section 1

INTRODUCTION

背景



1 Smart construction & digitalization 智能建造



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Smart construction as a national strategy

- 中央政府：“發展智能建造”——《十四五規劃和2035年遠景目標綱要》
- 國家自然資源部：《关于全面推进实景三维中国建设的通知》

NDC  国家数字建造技术创新中心 
National Center of Technology Innovation Digital Construction 工程管理研究所

In Hong Kong

- Election Manifesto of Chief Executive Election 2022
- Development Bureau's Technical Circular (2021)
- CIC's Construction Digitalization Roadmap (2021)
 - 6 Applications (DAs)



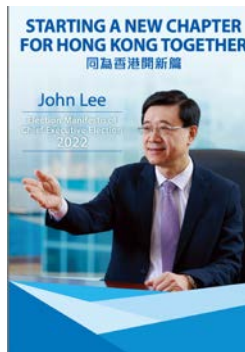
首页 > 新闻 > 滚动

中华人民共和国国民经济和社会发展第十四个五年规划和2035年远景目标纲要



| | |
|------|---------------------------|
| 名称 | 自然资源部办公厅关于全国新建实景三维中国建设的通知 |
| 索引号 | 000019174/2022-00046 |
| 发文字号 | 自然资办发〔2022〕7号 |
| 生成日期 | 2022年02月24日 |

20 December 2021





1 BIM is a key 关键



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◇ HK market: ~HK\$300 billion. 每年3000亿

◇ BIM in Hong Kong 越来越宽、越来越深

▣ “Wider” by industry-wide mandatory uses

○ 所有All public works >HK\$30M since 2020 (DevB, 2019)

○ 所有All private projects >HK\$300M by 2026 (CIC, 2022)

▣ “Deeper” for values

○ “A roadmap on BIM for plans submission” (Policy Addr 2022)

○ 20 mandatory BIM stages since 2022 (DevB, 2021)

◇ 3D point scans 激光点云 in top BIM uses

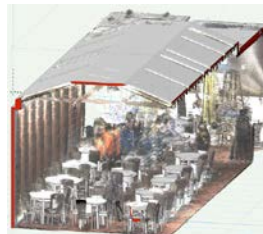
▣ Surveys actual 3D dimensions, real assets

▣ Every developer/contractor has a laser scan team

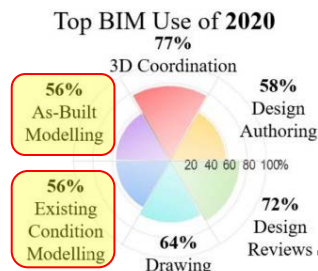
| BIM Use | Investigation, Feasibility and Planning | Design |
|--|---|----------------|
| 1 Design Authoring | M ^o | M |
| 2 Design Reviews | M ^o | M |
| 3 Existing Conditions Modelling | M ^o | M |
| 4 Site Analysis | M ^o | M |
| 5 3D Coordination | | M |
| 6 Cost Estimation | O | M ^o |
| 7 Engineering Analysis | | M ^o |
| 8 Facility Energy Analysis | | O |
| 9 Sustainability Evaluation | O | M ^o |
| 10 Space Programming | O | M ^o |
| 11 Phase Planning (4D Modelling) | | M ^o |
| 12 Digital Fabrication | | M ^o |
| 13 Site Utilization Planning | | |
| 14 3D Control and Planning | | |
| 15 As-Built Modelling | | |
| 16 Project Systems Analysis | | |
| 17 Maintenance Scheduling | | |
| 18 Space Management and Tracking | | |
| 19 Asset Management | | M ^o |
| 20 Drawing Generation (Drawing Production) | | M |



BIM mandatory stages (DevB TC(W) No. 2/2021)



Scan-to-BIM (Moon Palace, Src: authors)



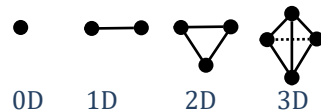
Top BIM uses in Hong Kong (Src: CIC)

1 What is a point cloud 点云



◆ Point 点

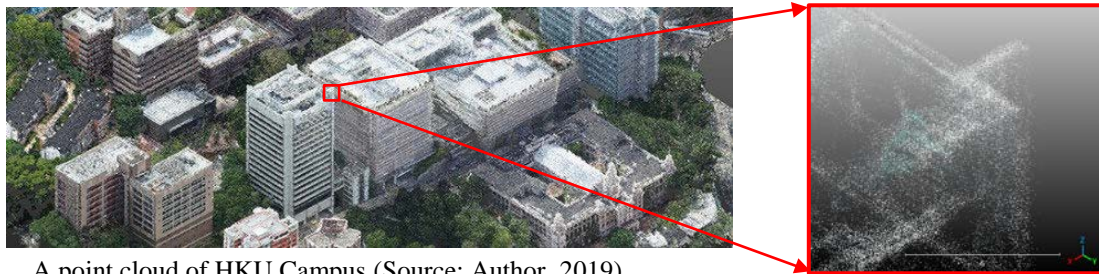
- ▣ A **location** in space, 0D (no width, length, or thickness)
- ▣ Structured format: $\{x, y, z\}$, $[R, G, B, N_x, N_y, N_z, Cls, Int., \dots]$



◆ Cloud 云

- ▣ An unstructured collection [of water droplets or ice crystals]
- ▣ Dense when looking at a distance, sparse closely

◆ Point cloud (PC)



A point cloud of HKU Campus (Source: Author, 2019)



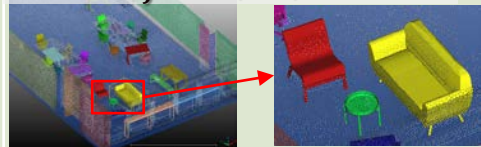


A close look of cloud at Mount Hua (Source: Author)



1 Existing scan-to-BIM paradigms 现存范式



| Paradigm | Key algorithm | Trained for HK | Software's output (Dimension of objects) | Labor-hour (30 rooms) | Applicability for BIM uses |
|---|---|----------------|--|----------------------------|--|
| 1. Open-source mesher + <i>ifcopenshell</i> | Poisson reconstruction | ✗ | Mesh triangles (2D)  | 200 | Visualization |
| 2. Aurivus® + open-source clustering | 3D Deep Learning (DL) | ✗ | Points with labels (3D)  | 140 (30% saved) | Visualization; Designed BIM verification; |
| 3. Proposed SBASE | Our 3D DL + frequent 3D BIM for HK | ✓ | BIM Objects (3D)  | 85 ✓ (60% saved) | Visualization; Designed BIM verification; BIM auditing; Lightweight CIM |

Reference BIM by a human modeler



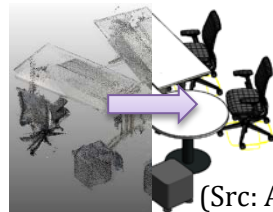
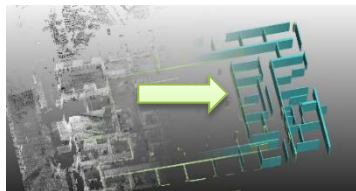


1 General workflow; 现存问题



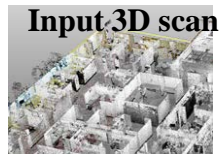
◇ 4 steps

- 1.1 Point-level 点级别
- 1.2 Primitive-level 几何块级别
- 1.3 3D BIM details 细节BIM
- 2. Applications 应用



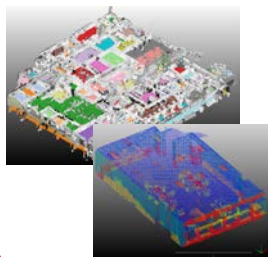
(Src: Authors)

Input: 3D scan



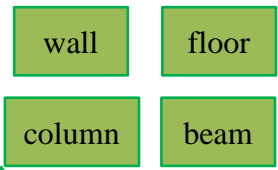
(Src: Authors)

1.1 Segmentation



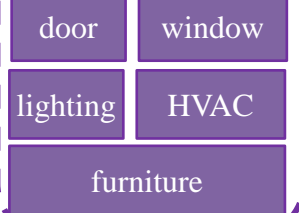
Time cost: ~5%

1.2 General architectural elements (AEs)



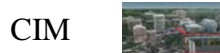
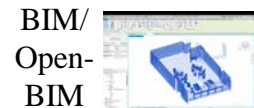
Time cost: ~20%

1.3 Detailed BIM objects



Time cost: ~75%

2. Applications



(Src: Authors)

1. *mesher* + *ifcopenshell*

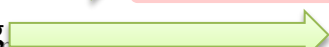


Not covered



Not covered

2. *Aurivus*® + *clustering*



Not covered

Section 2

TYPES OF MACHINE LEARNING

概述

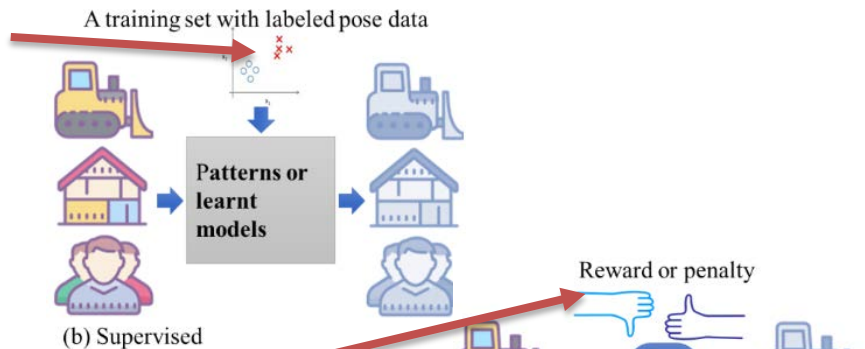


2 3 types of ML 机器学习三大类



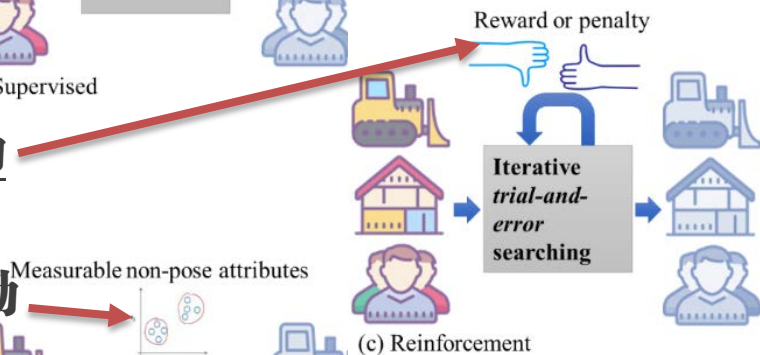
Supervised learning 监督：须标注数据

- Classification and regression
- Meta learning
- Automated ML (AutoML)
- Deep learning



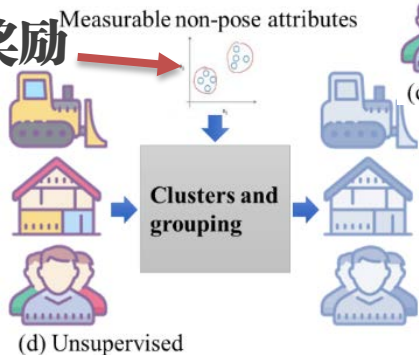
Reinforcement learning 强化：无标注有奖励

- Simulation-based optimization



Unsupervised learning 无监督：无标注无奖励

- Clustering
- Association rules



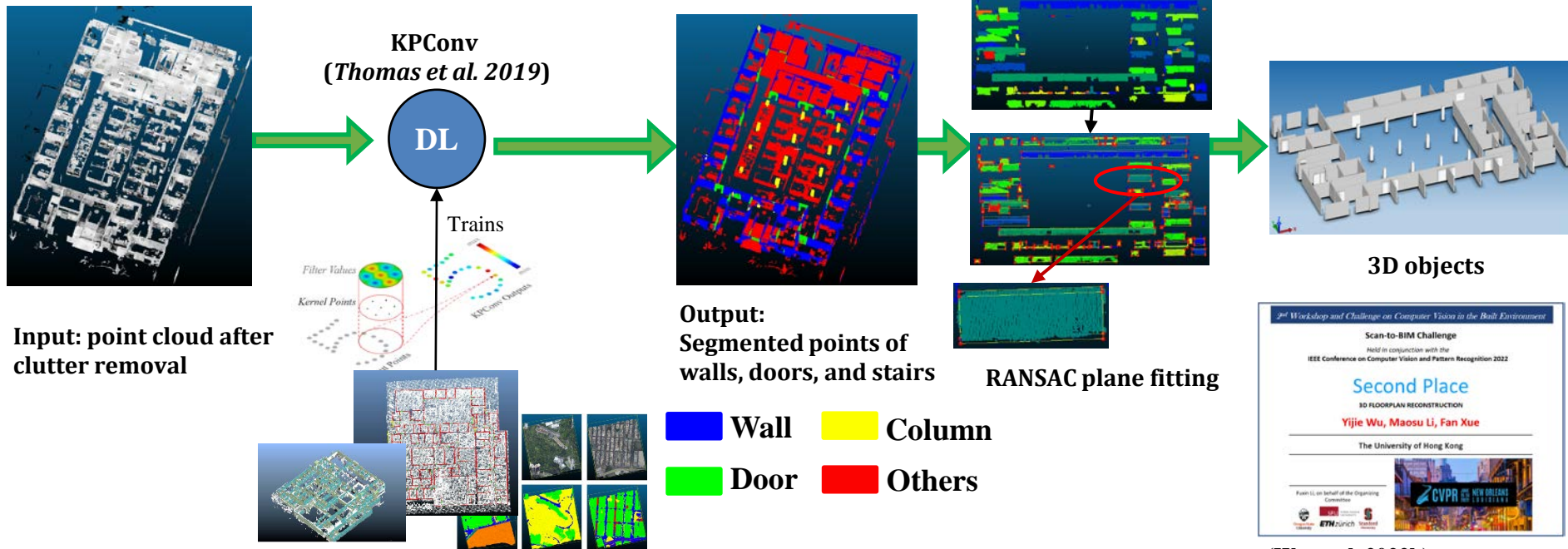


2.1 Supervised segmentation 监督：须标注数据



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◇ ‘KP’ of FLKPP: Kernels of points



Xue: Fully auto scan2BIM. Wuhan, China. 2023.



(Wu et al. 2022b)

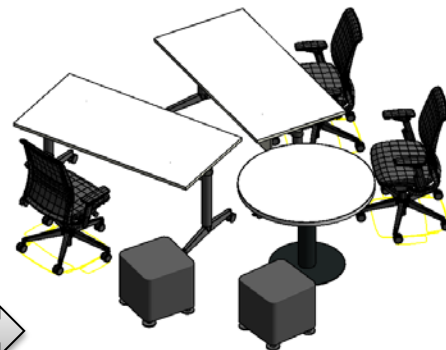
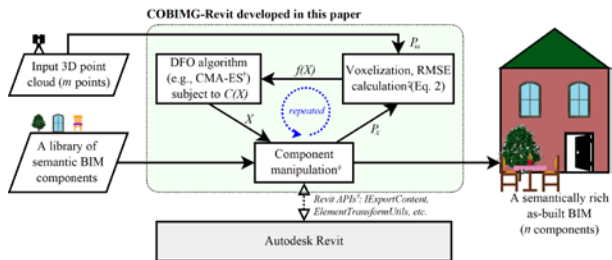


2.2 Reinforcement 3D pose 强化：无标注有奖励 (Xue et al. 2019b)

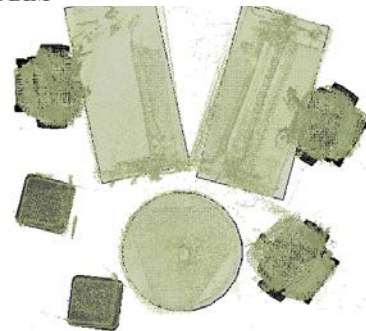
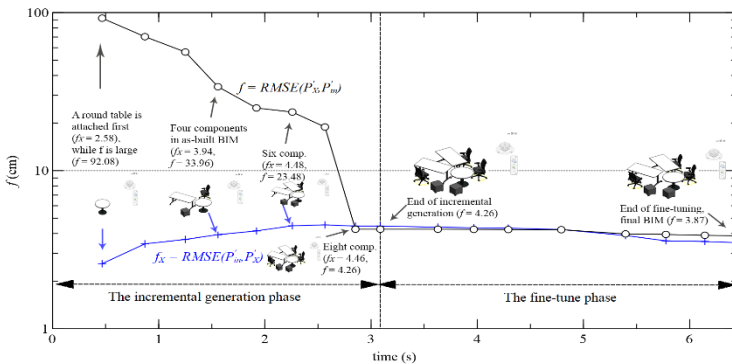
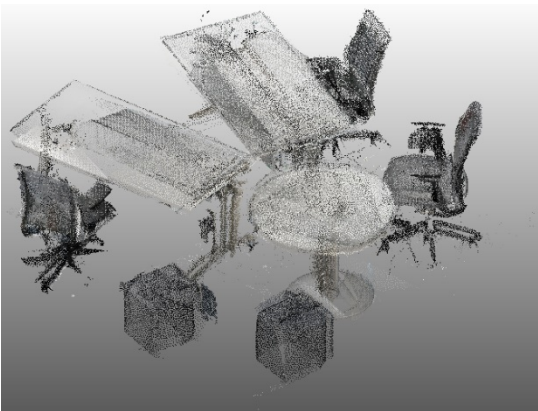


◆ 惩罚：BIM与点云匹配误差

▣ Time = 6.44s (Manual = 300s), RMSE = 3.87 cm



(a) A screenshot of the 3D view of the output as-built BIM



(b) A visual comparison between the input (grey points) and the output BIM

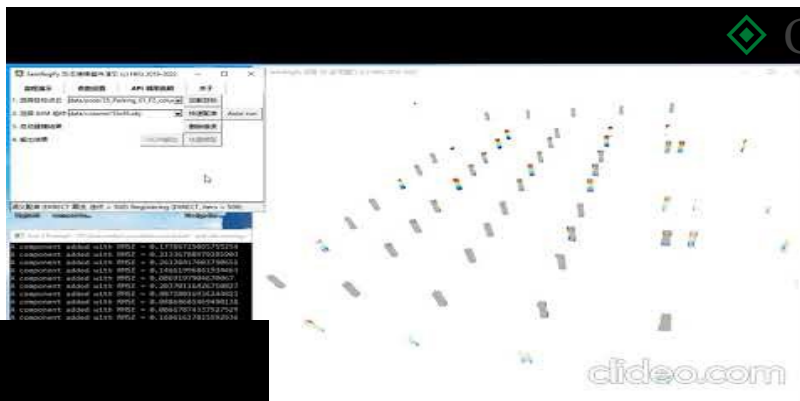


2.2 Reinforcement 3D pose 强化：demo



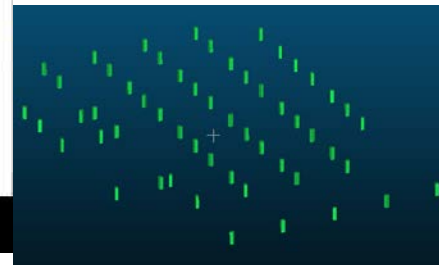
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Fitting BIM objects for location, rotation, and relational semantics (Xue 2019)



◇ Output formats

- ▣ BIM
- ▣ JSON



Another demo of 3D pose estimation of columns (Wu et al. 2022b; <https://youtu.be/kdMYD0P67kY>)

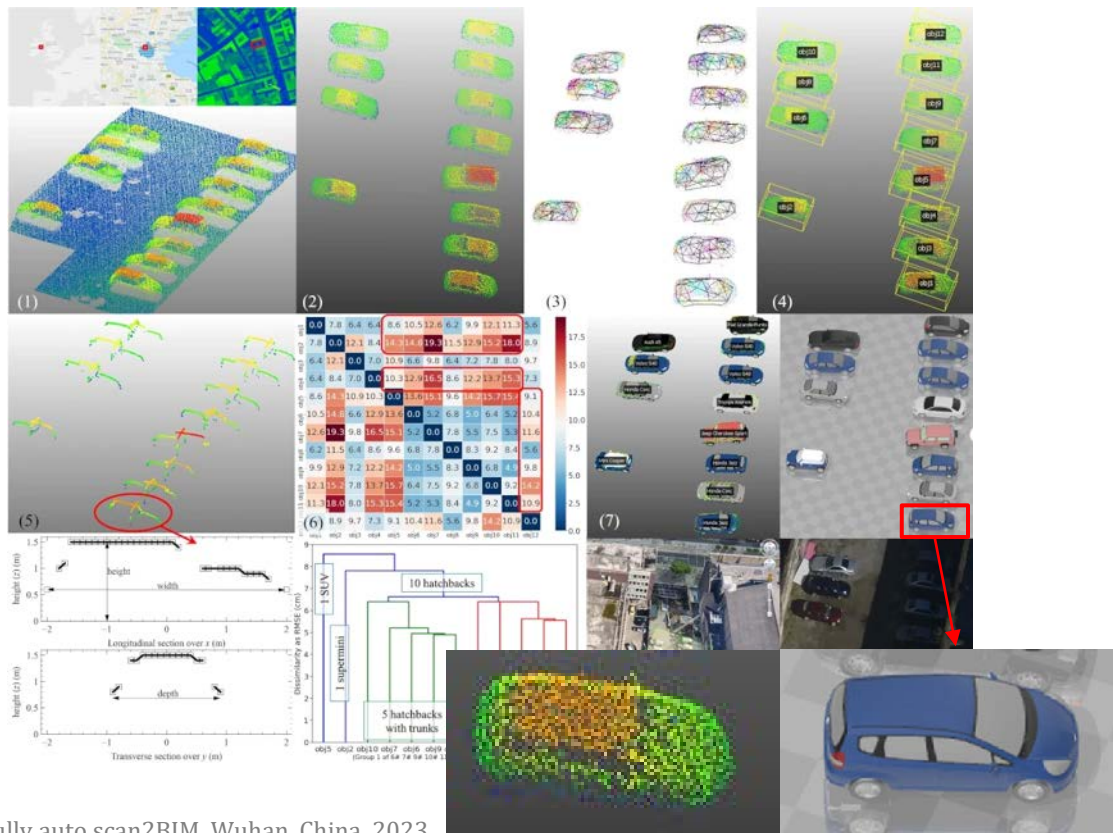
```

{
  "model": "data/column/55x45.obj",
  "translation": [
    1.8909524635450943,
    31.772408610437388,
    1.4906147914442662
  ],
  "rotation": [
    0,
    0,
    0.0
  ]
},
{
  "model": "data/column/55x45.obj",
  "translation": [
    1.8909524635450943,
    31.772408610437388,
    1.4906147914442662
  ],
  "rotation": [
    0,
    0,
    0.0
  ]
}

```



2.3 Unsupervised clustering 无监督：无标注无奖励



- ◇ Ground (planar) removal
- ◇ Clustering patches
- ◇ Symmetry detection
 - ▣ By optimization (RL)
 - ▣ For cross-sections
 - ▣ Longitudinal / transverse
- ◇ Clustering objects using cross-sections
 - ▣ 无成本，快速
- ◇ Fitting 3D model



2.3 Unsupervised clustering 无监督：无标注无奖励



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◇ ‘FL’ of FLKPP: floor layers

▣ Room clustering 聚合室内“空间”

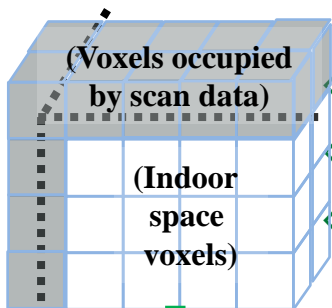
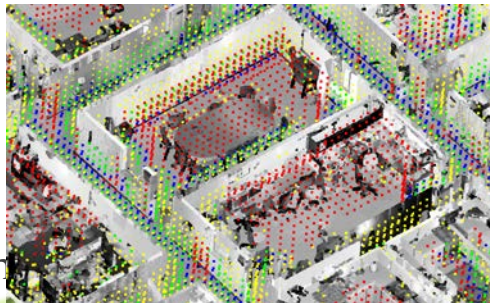
▣ Room-base noise and clutter removal 去噪

◇ Space voxels labeling

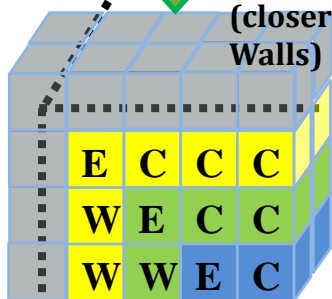
◇ Region growing to segment rooms

◇ Clutter removal (using head levels in room)

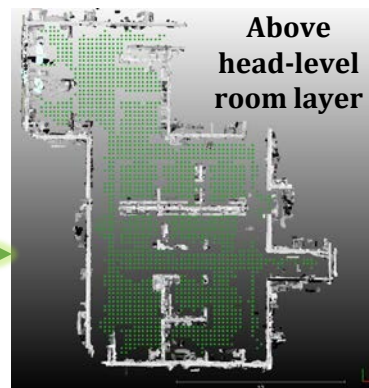
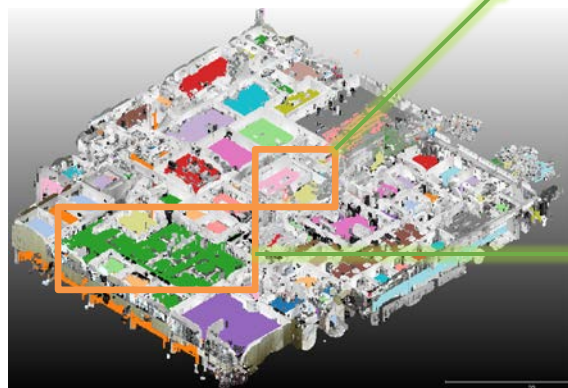
(Zoom-in)



1. Space voxels (closer to Edge, Ceiling, Walls)



2. Room clustering (using voxels 1m to ceilings)



Section 3

AUTOMATIC SCAN-TO-BIM

全自动化

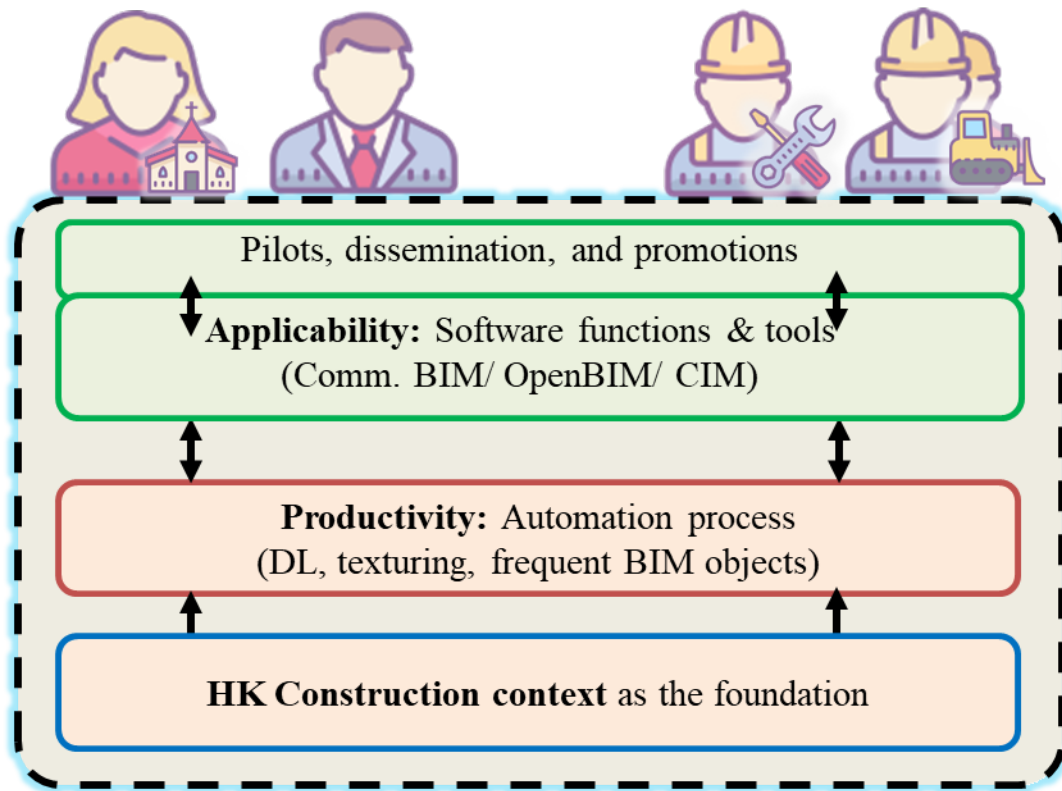


3 SBASE项目 : Fully automation



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- ◇ SBASE 项目
 - ▣ Scan-to-BIM Auto System
- ◇ Step 1.1 :
 - ▣ Unsupervised + supervised
- ◇ Step 1.2:
 - ▣ Unsupervised + rules
- ◇ Step 1.3:
 - ▣ Unsupervised + reinforcement
- ◇ Step 2:
 - ▣ Localized apps





3.1 SBASE 项目: Funding and team



◆ Funding

- ▣ Hong Kong ITF Tier-1: HK\$ 7.51M (in total 751万) 2023-2025

◆ Team

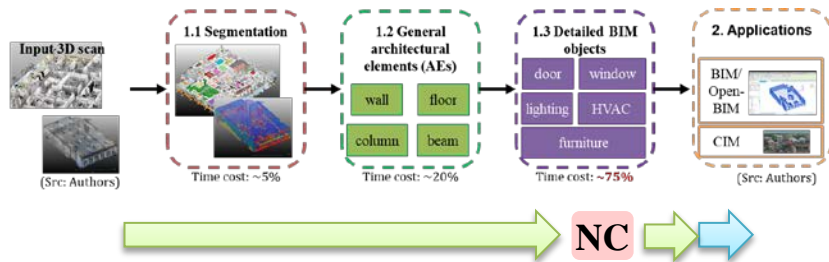
- ▣ PC 主持: F Xue
- ▣ Co-PI: Prof Anthony Yeh 叶嘉安院士
- ▣ Co-PI: Prof Wilson Lu 吕伟生教授
- ▣ Co-I: Dr Ke Chen 陈珂 (华科)



◆ Automation level: Full, limitations in 1.3

◆ Job vacancies 虚位以待

- ▣ Postdoc 博士后 1 名
- ▣ RA 助理研究 6 名





3.2 A recap



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◆ Scan-to-BIM

- ▣ Vital to smart construction
- ▣ Automation is limited currently

◆ Types of Machine Learning “训练?”

- ▣ Supervised: 3D语义分割
- ▣ Reinforcement: 最佳BIM族匹配
- ▣ Unsupervised: 对比、聚类

◆ Auto scan-to-BIM “综合”

- ▣ Consolidation 按需求整合
- ▣ Huge potentials 大有可为





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Keep awesome!

感谢！ 欢迎提问

